Midterm Review

Topics on the Midterm

- Data Structures & Object-Oriented Design
- Run-Time Analysis
- Linear Data Structures
- The Java Collections Framework
- Recursion
- Trees
- Priority Queues & Heaps

Data Structures So Far

- Array List
  - (Extendable) Array
- Node List
  - Singly or Doubly Linked List
- Stack
  - Array
  - Singly Linked List
- Queue
  - Array
  - Singly or Doubly Linked List
- Priority Queue
  - Unsorted doubly-linked list
  - Sorted doubly-linked list
  - Heap (array-based)
- Adaptable Priority Queue
  - Sorted doubly-linked list with location-aware entries
  - Heap with location-aware entries
- Tree
  - Linked Structure
- Binary Tree
  - Linked Structure
  - Array

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Data Structures & Object-Oriented Design

- Definitions
- Principles of Object-Oriented Design
- Hierarchical Design in Java
- Abstract Data Types & Interfaces
- Casting
- Generics
- Pseudo-Code

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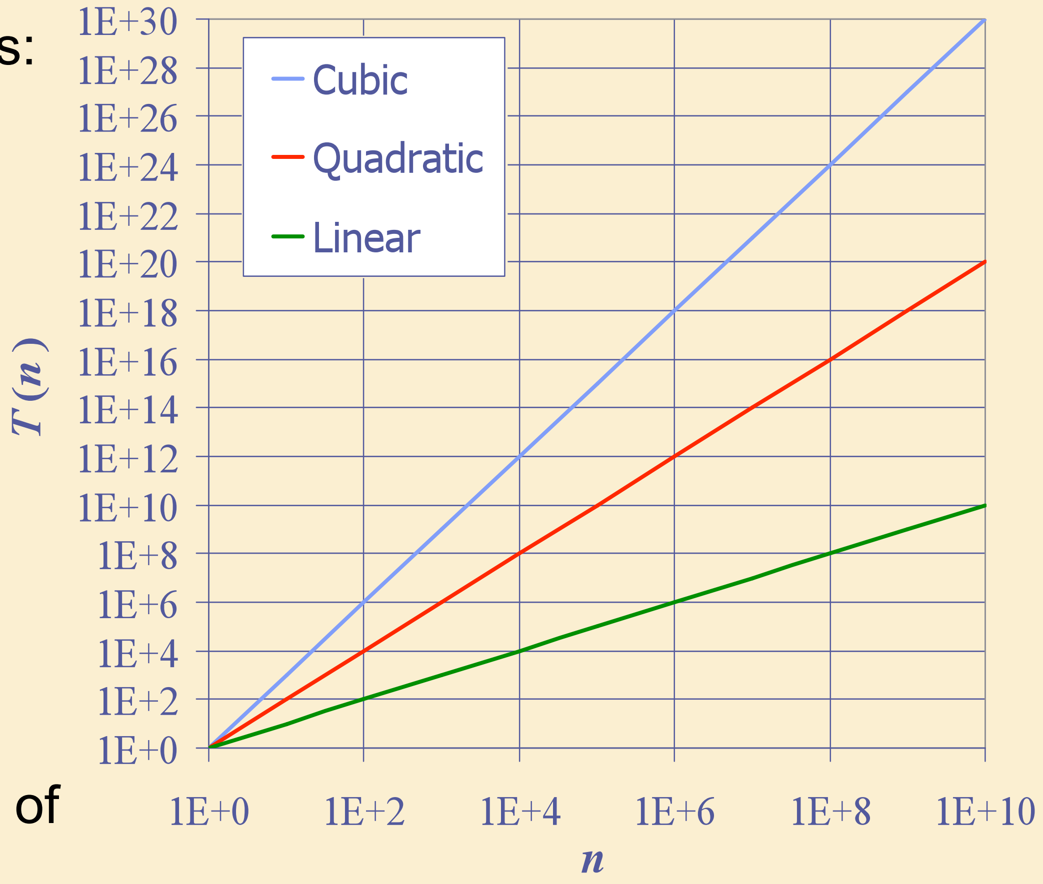
Seven Important Functions

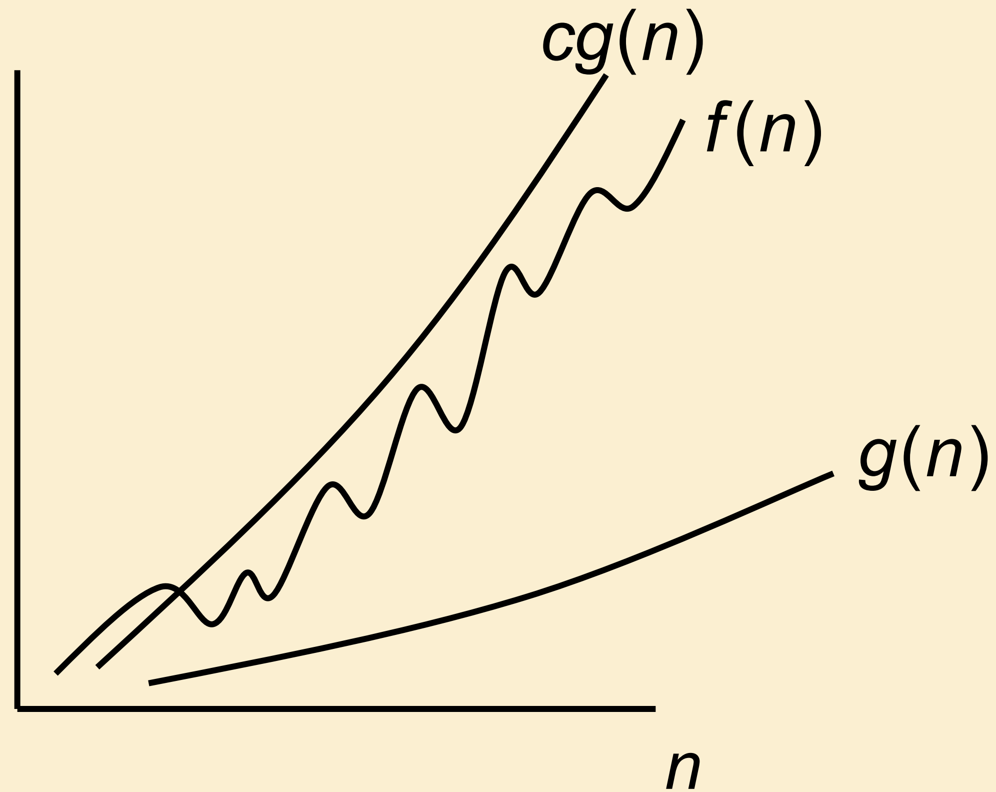
- Seven functions that often appear in algorithm analysis:
  - Constant ≈ *1*
  - Logarithmic ≈ log n
  - Linear ≈ n
  - N-Log-N ≈ n log n
  - Quadratic ≈ n^2
  - Cubic ≈ n^3
  - Exponential ≈ 2^n



- In a log-log chart, the slope of the line corresponds to the growth rate of the function.

Definition of "Big Oh"

$$f(n) \in O(g(n))$$



$$\exists c, n_0 > 0 : \forall n \geq n_0, f(n) \leq cg(n)$$

Relatives of Big-Oh

- **big-Omega**
  - f(n) is $\Omega(g(n))$ if there is a constant $c > 0$ and an integer constant $n_0 \geq 1$ such that $f(n) \geq c \cdot g(n)$ for $n \geq n_0$
- **big-Theta**
  - f(n) is $\Theta(g(n))$ if there are constants $c_1 > 0$ and $c_2 > 0$ and an integer constant $n_0 \geq 1$ such that $c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n)$ for $n \geq n_0$

Time Complexity of an Algorithm

The time complexity of an algorithm is the *largest* time required on *any* input of size n. (Worst case analysis.)

- $O(n^2)$: For any input size $n \geq n_0$, the algorithm takes no more than cn^2 time on every input.
- $\Omega(n^2)$: For any input size $n \geq n_0$, the algorithm takes at least cn^2 time on at least one input.
- $\theta\ (n^2)$: Do both.

Time Complexity of a Problem

The time complexity of a problem is the time complexity of the *fastest* algorithm that solves the problem.

- $O(n^2)$: Provide an algorithm that solves the problem in no more than this time.
  - Remember: for every input, i.e. worst case analysis!
- $\Omega(n^2)$: Prove that no algorithm can solve it faster.
  - Remember: only need one input that takes at least this long!
- $\theta(n^2)$: Do both.

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Linear Data Structures

- Fundamental Data Structures
  - Arrays
  - Singly-Linked Lists
  - Doubly-Linked Lists
- Abstract Data Types
  - Array Lists
  - Stacks
  - Queues

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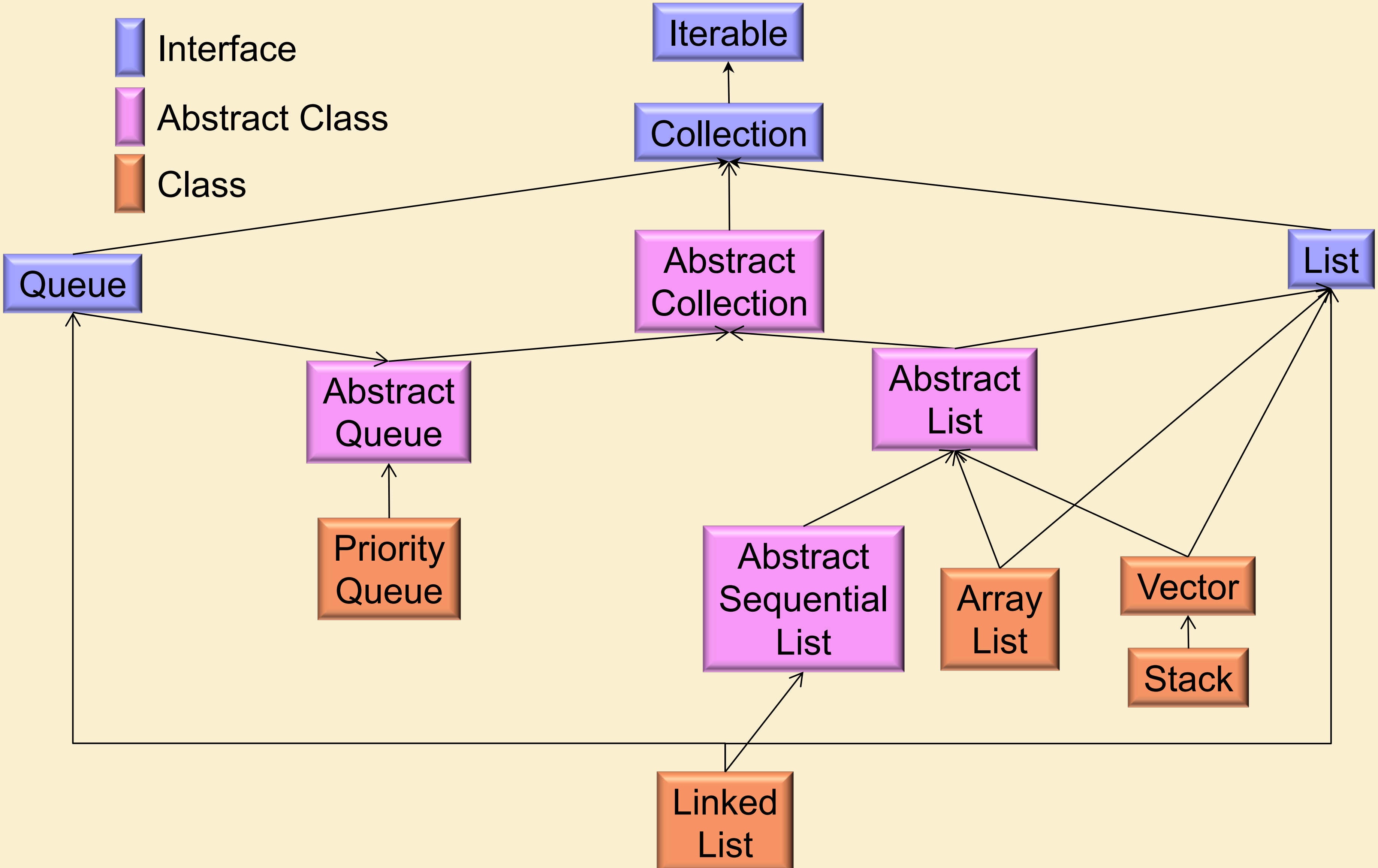
Iterators

- An Iterator is an object that enables you to traverse through a collection and to remove elements from the collection selectively, if desired.
- You get an Iterator for a collection by calling its iterator method.
- Suppose **collection** is an instance of a **Collection**. Then to print out each element on a separate line:

```
Iterator<E> it = collection.iterator();
while (it.hasNext())
    System.out.println(it.next());
```

The Java Collections Framework (Ordered Data Types)



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Linear Recursion Design Pattern

- **Test for base cases**
  - Begin by testing for a set of base cases (there should be at least one).
  - Every possible chain of recursive calls **must** eventually reach a base case, and the handling of each base case should not use recursion.
- ***Recurse once***
  - Perform a single recursive call. (This recursive step may involve a test that decides which of several possible recursive calls to make, but it should ultimately choose to make just one of these calls each time we perform this step.)
  - Define each possible recursive call so that it makes **progress** towards a base case.

Binary Recursion

- Binary recursion occurs whenever there are **two** recursive calls for each non-base case.
- Example 1: **The Fibonacci Sequence**

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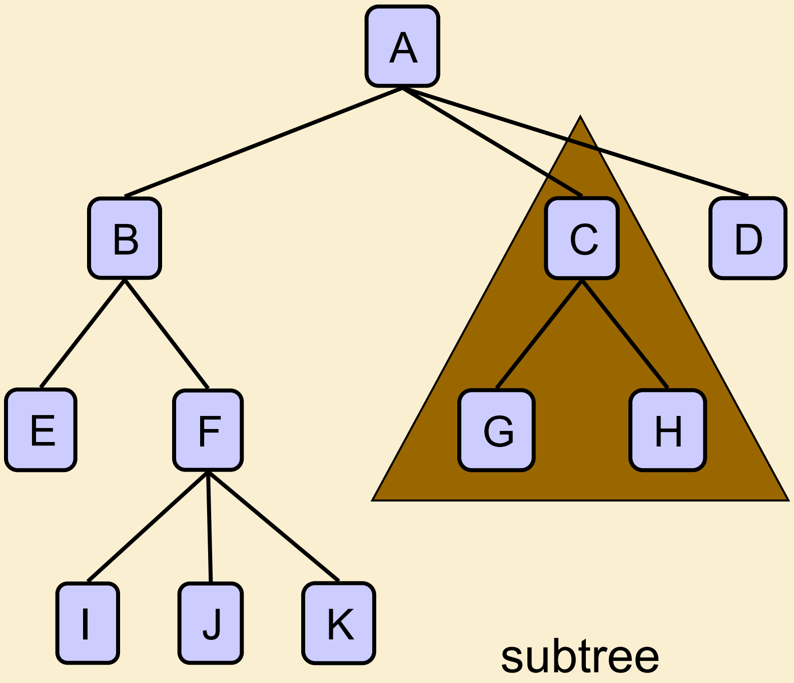
Tree Terminology

- **Root:** node without parent (A)
- **Internal node:** node with at least one child (A, B, C, F)
- **External node (a.k.a. leaf):** node without children (E, I, J, K, G, H, D)
- **Ancestors of a node:** parent, grandparent, grand-grandparent, etc.
- **Descendant of a node:** child, grandchild, grand-grandchild, etc.
- **Siblings**: two nodes having the same parent
- **Depth of a node:** number of ancestors (excluding self)
- **Height of a tree:** maximum depth of any node (3)
- **Subtree:** tree consisting of a node and its descendants



Position ADT

- The Position ADT models the notion of place within a data structure where a single object is stored
- It gives a unified view of diverse ways of storing data, such as
  - a cell of an array
  - a node of a linked list
  - a node of a tree
- Just one method:
  - object element(): returns the element stored at the position

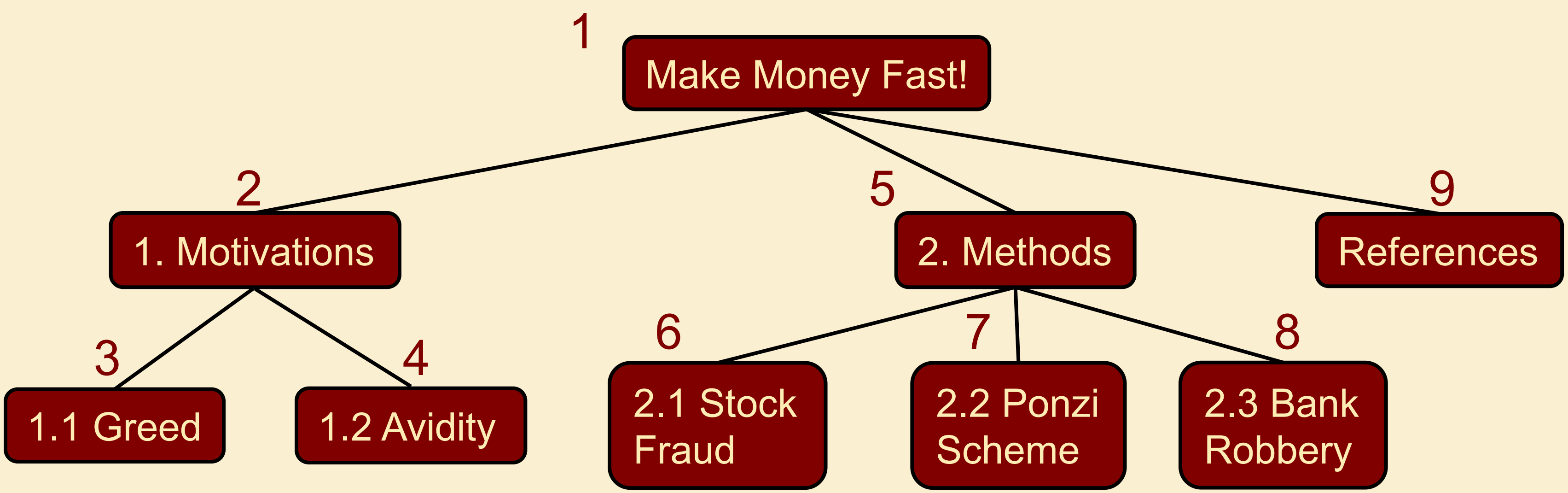
Tree ADT

- We use positions to abstract nodes
- Generic methods:
  - integer size()
  - boolean isEmpty()
  - Iterator iterator()
  - Iterable positions()
- Accessor methods:
  - position root()
  - position parent(p)
  - positionIterator children(p)
- Query methods:
  - boolean isInternal(p)
  - boolean isExternal(p)
  - boolean isRoot(p)
- Update method:
  - object replace(p, o)
  - Additional update methods may be defined by data structures implementing the Tree ADT

Preorder Traversal

- A traversal visits the nodes of a tree in a systematic manner
- In a preorder traversal, a node is visited before its descendants

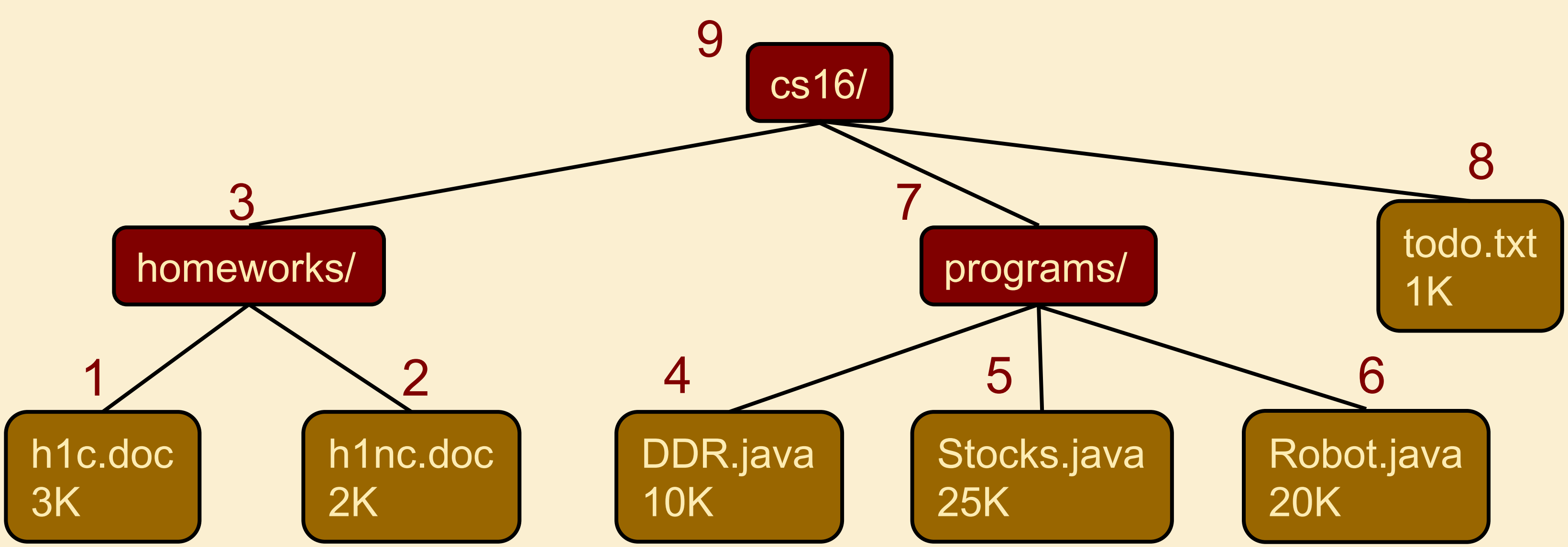
Algorithm ***preOrder***(***v***)
    visit(***v***)
    for each child ***w*** of ***v***
        preOrder (***w***)



Postorder Traversal

- In a postorder traversal, a node is visited after its descendants

```
Algorithm postOrder(v)
    for each child w of v
        postOrder (w)
    visit(v)
```



Properties of Proper Binary Trees

- Notation

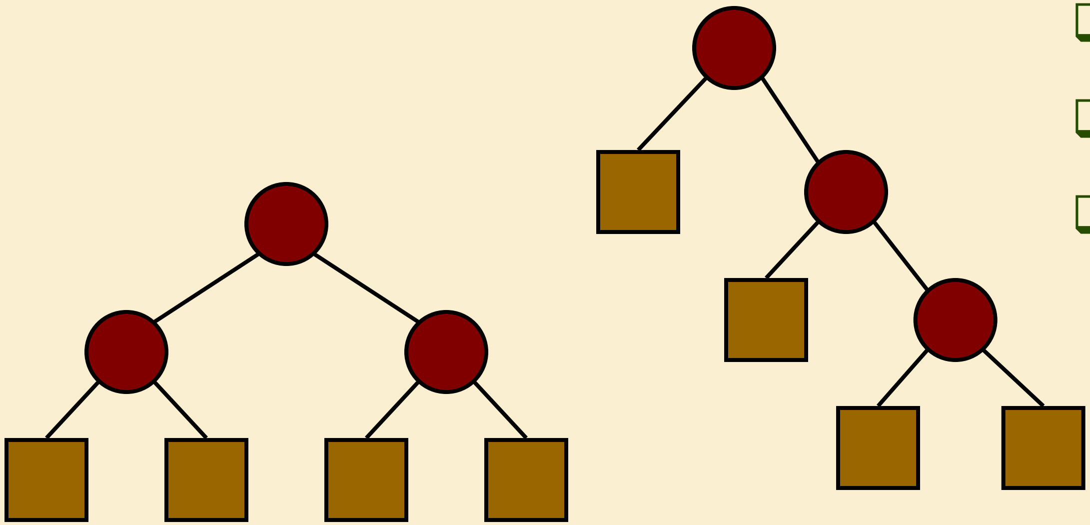
  n number of nodes

  e number of external nodes

  i number of internal nodes

  h height

- Properties:
  - $e = i + 1$
  - $n = 2e - 1$
  - $h \leq i$
  - $h \leq (n - 1)/2$
  - $e \leq 2^h$
  - $h \geq \log_2 e$
  - $h \geq \log_2(n + 1) - 1$



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Priority Queue ADT

- A priority queue stores a collection of **entries**
- Each **entry** is a pair (key, value)
- Main methods of the Priority Queue ADT
  - **insert**(k, x) inserts an entry with key k and value x
  - **removeMin**() removes and returns the entry with smallest key
- Additional methods
  - **min**() returns, but does not remove, an entry with smallest key
  - **size**(), **isEmpty**()
- Applications:
  - Process scheduling
  - Standby flyers

Comparator ADT

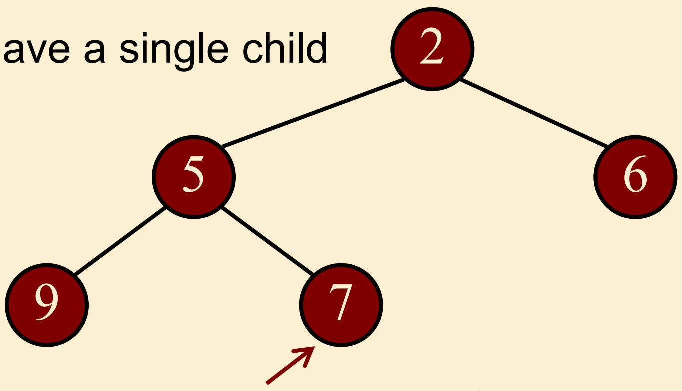
- A comparator encapsulates the action of comparing two objects according to a given total order relation
- A generic priority queue uses an auxiliary comparator
- The comparator is external to the keys being compared
- When the priority queue needs to compare two keys, it uses its comparator
- The primary method of the Comparator ADT:
  - **compare**(a, b):
    - Returns an integer *i* such that
      - $i < 0$ if $a < b$
      - $i = 0$ if $a = b$
      - $i > 0$ if $a > b$
      - an error occurs if *a* and *b* cannot be compared.

Heaps

- Goal:
  - O(log n) insertion
  - O(log n) removal
- Remember that O(log n) is almost as good as O(1)!
  - e.g., n = 1,000,000,000 → log n ≅ 30
- There are min heaps and max heaps. We will assume min heaps.

Min Heaps

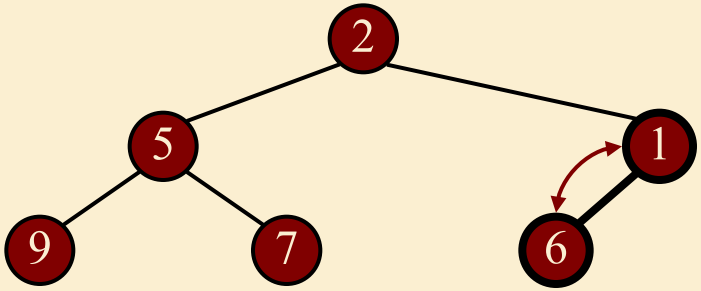
- A min heap is a binary tree storing keys at its nodes and satisfying the following properties:
  - Heap-order: for every internal node v other than the root
    - $key(v) \geq key(parent(v))$
  - (Almost) complete binary tree: let h be the height of the heap
    - for $i = 0, \ldots, h - 1$, there are 2^i nodes of depth i
    - at depth $h - 1$
      - the internal nodes are to the left of the external nodes
      - Only the rightmost internal node may have a single child

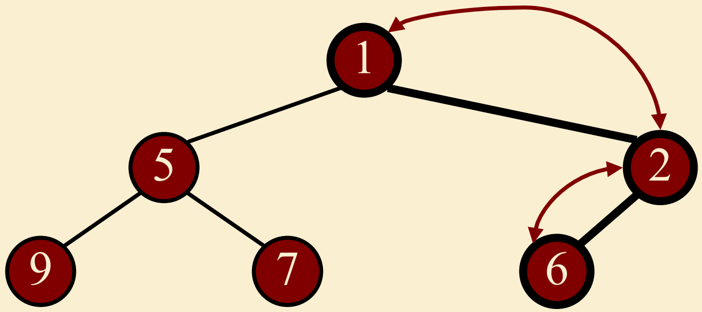


- **The last node of a heap is the rightmost node of depth h**

Upheap

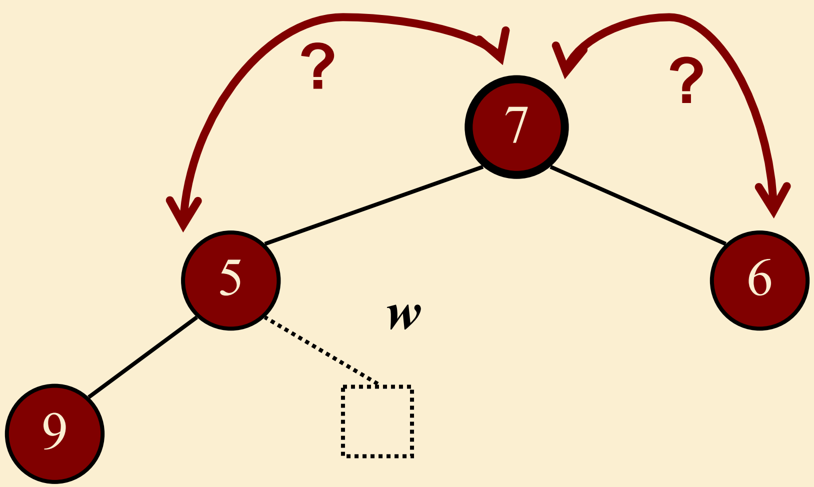
- After the insertion of a new key k, the heap-order property may be violated
- Algorithm **upheap** restores the heap-order property by swapping k along an upward path from the insertion node
- **Upheap** terminates when the key k reaches the root or a node whose parent has a key smaller than or equal to k
- Since a heap has height $O(\log n)$, **upheap** runs in $O(\log n)$ time





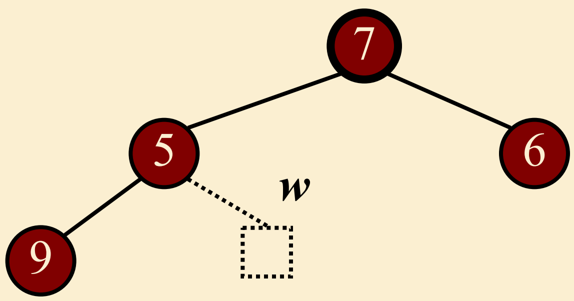
Downheap

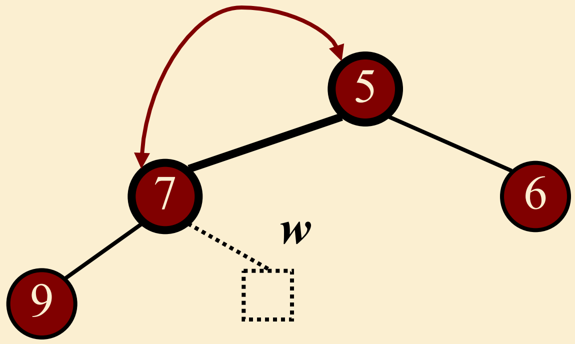
- After replacing the root key with the key k of the last node, the heap-order property may be violated
- Algorithm downheap restores the heap-order property by swapping key k along a downward path from the root
- Note that there are, in general, many possible downward paths – which one do we choose?



Downheap

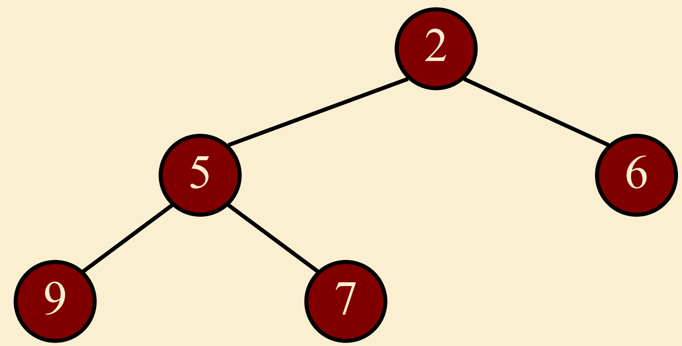
- We select the downward path through the **minimum-key** nodes.
- Downheap terminates when key k reaches a leaf or a node whose children have keys greater than or equal to k
- Since a heap has height $O(\log n)$, downheap runs in $O(\log n)$ time

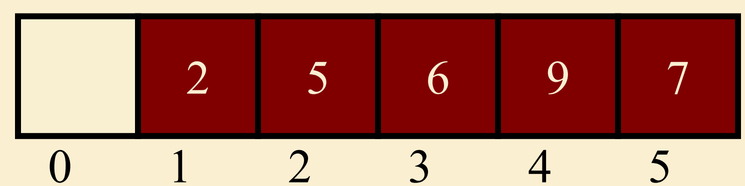




Array-based Heap Implementation

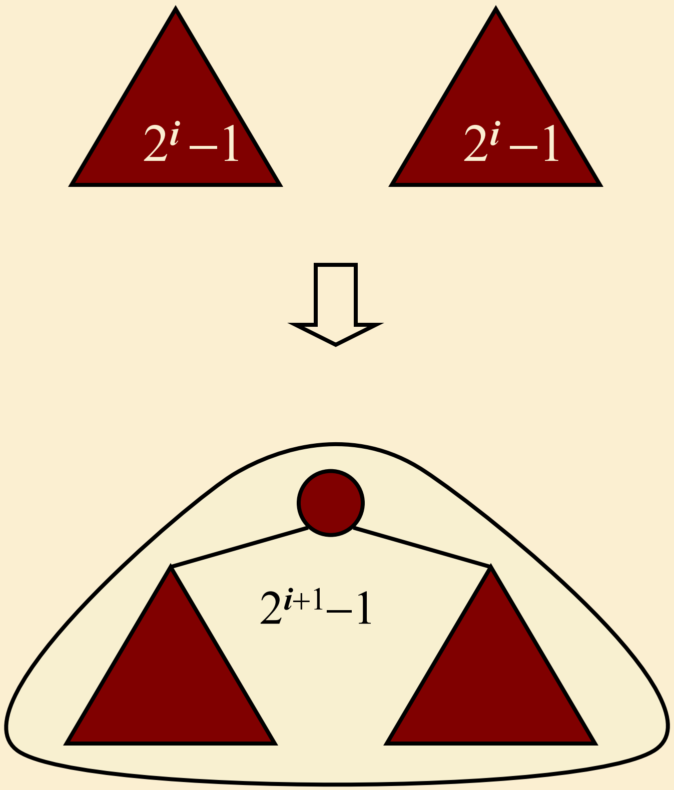
- We can represent a heap with n keys by means of an array of length $n + 1$
- Links between nodes are not explicitly stored
- The cell at rank 0 is not used
- The root is stored at rank 1.
- For the node at rank i
  - the left child is at rank $2i$
  - the right child is at rank $2i + 1$
  - the parent is at rank **floor**(i/2)
  - if 2i + 1 > n, the node has no right child
  - if 2i > n, the node is a leaf



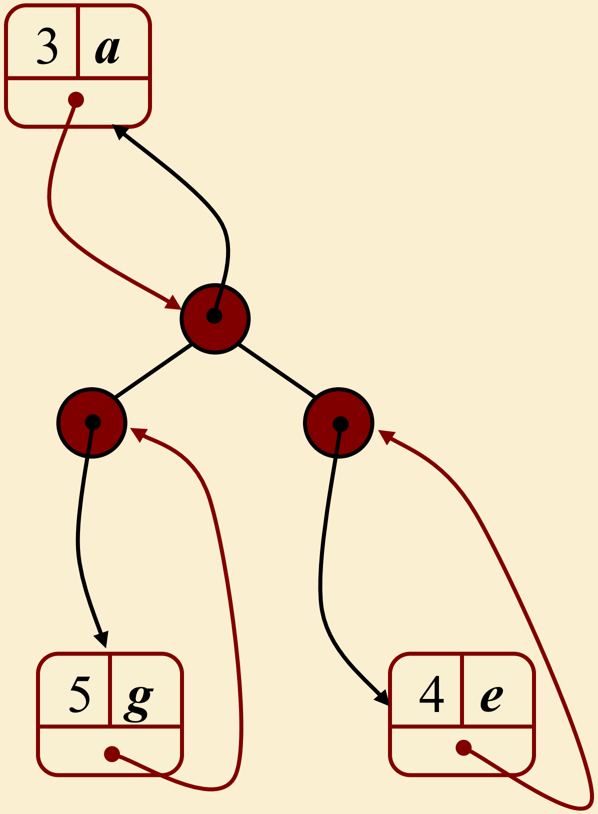


Bottom-up Heap Construction

- We can construct a heap storing n keys using a bottom-up construction with $\log n$ phases
- In phase i, pairs of heaps with $2^i - 1$ keys are merged into heaps with $2^{i+1} - 1$ keys
- Run time for construction is $O(n)$.



Adaptable Priority Queues



Additional Methods of the Adaptable Priority Queue ADT

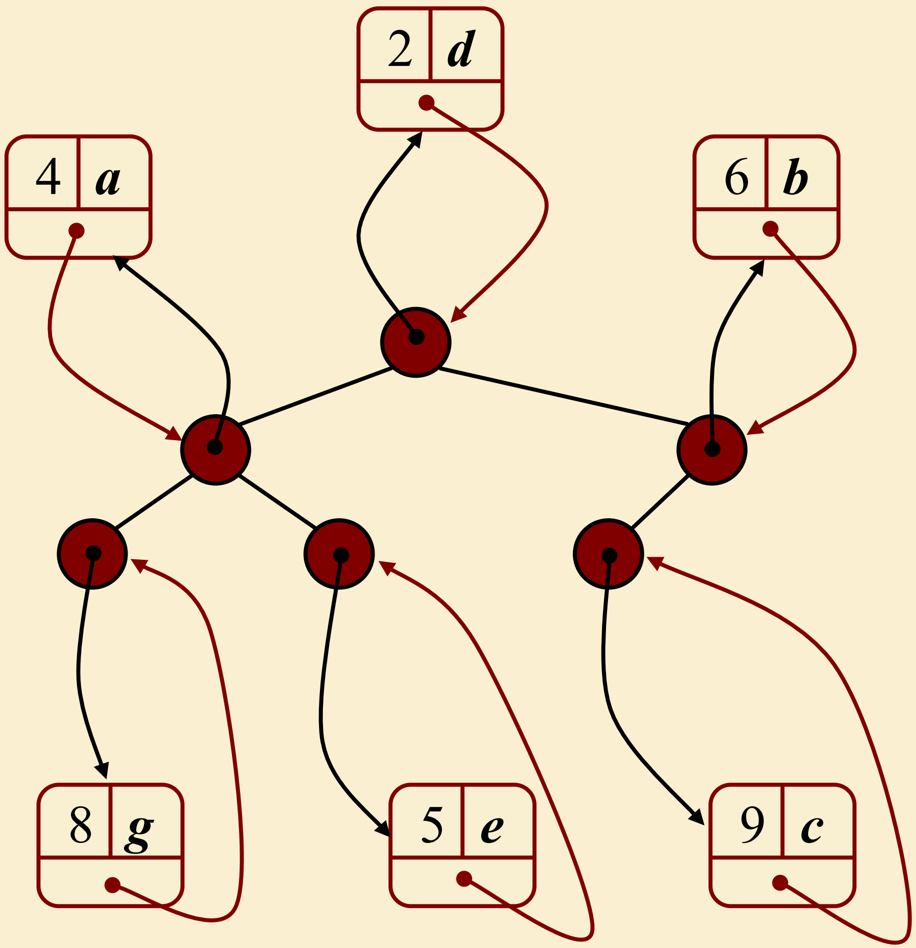
- remove(*e*): Remove from *P* and return entry *e*.
- replaceKey(*e,k*): Replace with *k* and return the old key*;* an error condition occurs if *k* is invalid (that is, *k* cannot be compared with other keys).
- replaceValue(*e,x*): Replace with *x* and return the old value.

Location-Aware Entries

- A locator-aware entry identifies and tracks the location of its (key, value) object within a data structure

Heap Implementation

- A location-aware heap entry is an object storing
  - key
  - value
  - position of the entry in the underlying heap
- In turn, each heap position stores an entry
- Back pointers are updated during entry swaps



Performance

- Times better than those achievable without location-aware entries are highlighted in red:

Method	Unsorted List	Sorted List	Heap
size, isEmpty	$O(1)$	$O(1)$	$O(1)$
insert	$O(1)$	$O(n)$	$O(\log n)$
min	$O(n)$	$O(1)$	$O(1)$
removeMin	$O(n)$	$O(1)$	$O(\log n)$
remove	**$O(1)$**	**$O(1)$**	**$O(\log n)$**
replaceKey	**$O(1)$**	$O(n)$	**$O(\log n)$**
replaceValue	**$O(1)$**	**$O(1)$**	**$O(1)$**

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